An old Jewish philosopher once said, “Ask me any question, and if I know the answer, I will answer it. And, if I don’t know the answer, I’ll answer it anyway.” Me too. I think I know the answer to all control questions. The only problem is, a lot of my answers are wrong.

I’ve learned to differentiate between wrong and right answers by trial and error. If the panel board operator persistently prefers to run a new control loop that I’ve designed in manual, if he switches out of auto whenever the flow becomes erratic, then I’ve designed a control strategy that’s wrong. So, that’s how I’ve learned to discriminate between a control loop that works and a control strategy best forgotten.

Here’s something else I’ve learned. Direct from Dr. Shinsky, the world’s expert on process control:

- “Lieberman, if it won’t work in manual, it won’t work in auto.”
- “Most control problems are really process problems.”

I’ve no formal training in process control and instrumentation. All I know is what Dr. Shinsky told me. And 54 years of experience in process plants has taught me that’s all I need to know.
LEARNING FROM PLANT OPERATORS

My first assignment as a Process Engineer was on No. 12 Pipe Still in Whiting, Indiana. This was a crude distillation unit. My objective was to maximize production of gas oil, as shown in Figure 1-1. The gas oil had a product spec of not more than 500 ppm asphaltines. The lab required half a day to report sample results. However, every hour or two the outside operator brought in a bottle of gas oil for the panel board operator. The panel operator would adjust the wash oil flow, based on the color of the gas oil.

While plant supervision monitored the lab asphaltine sample results, plant operators ignored this analysis. They adjusted the wash oil rate to obtain a clean-looking product. The operators consistently produced a gas oil product with 50–200 ppm asphaltines. They were using too much wash oil. And the more the wash oil used, the lower the gas oil production.

I mixed a few drops of crude tower bottoms in the gas oil to obtain a bottle of 500 ppm asphaltine material. I then instructed the panel board operators as follows:

- If the sample from the field is darker than my standard bottle, increase the wash oil valve position by 5%.
- If the sample of gas oil from the field is lighter than my standard, decrease the wash oil valve position by 3%.
- Repeat the above every 30 minutes.

The color of gas oil from a crude distillation unit correlates nicely with asphaltine content. The gas oil, when free of entrained asphaltines, is a pale yellow. So, it seems that my procedure should have worked. But it didn’t. The operators persisted in drawing the sample every 1–2 hours.

![Diagram of wash oil flow](image-url)
So, I purchased an online colorimeter. The online colorimeter checked whether the gas oil color was above or below my set point. With an interval of 10 minutes, it would move the wash oil valve position by 1%. This never achieved the desired color, but the gas oil product was mixed in a tank. The main result was that gas oil production was maximized consistent with the 500 ppm asphaltine specification.

One might say that all I did was automate what the operators were already doing manually, that all I accomplished was marginally improving an existing control strategy by automating the strategy. But in 1965 I was very proud of my accomplishments. I had proved, as Dr. Shinsky said, “If it does work on manual, we can automate it.”

LEARNING FROM FIELD OBSERVATIONS

Forty-eight years ago I redesigned the polypropylene plant in El Dorado, Arkansas. I had never paid much attention to control valves. I had never really observed how they operate. But I had my opportunity to do so when the polypropylene plant was restarted.

The problem was that the purchased propylene feed valve was too large for normal service. I had designed this flow for a maximum of 1600 BSD, but the current flow was only 100 BSD. Control valve response is quite nonlinear. Nonlinear means that if the valve is open by 5%, you might get 20% of the flow. If you open the valve from 80 to 100%, the flow goes up by an additional 2%. Nonlinear response also means that you cannot precisely control a flow if the valve is mostly closed. With the flow only 20% of the design flow, the purchased propylene feed was erratic. This resulted in erratic reactor temperature and erratic viscosity of the polypropylene product.

The plant start-up had proceeded slowly. It was past midnight. The evening was hot, humid, and very dark. I went out to look at the propylene feed control valves. Most of the flow was coming from the refinery’s own propylene supply. This valve was half open. But the purchased propylene feed valve was barely open. The valve position indicator, as best I could see with my flashlight, was bumping up and down against the “C” (closed) on the valve stem indicator.

The purchased propylene charge pump had a spillback line, as shown in Figure 1-2. I opened the spillback valve. The pump discharge pressure dropped, and the propylene feed valve opened to 30%. The control valve was now operating in its linear range.

Now, when I design a control valve to handle a large reduction in flow, I include an automated spillback valve from pump discharge to suction. The spillback controls the pump discharge pressure to keep the FRC valve between 20 and 80% open. Whenever I sketch this control loop I recall that dark night in El Dorado. I also recall the value of learning even the most basic control principles by personal field observations.
LEARNING FROM EXPERIENCE

LEARNING FROM MISTAKES

Adolf Hitler did not always learn from his mistakes. For example, he once ordered a submarine to attack the Esso Lago Refinery in Aruba. The sub surfaced in the island’s harbor and fired at the refinery. But the crew neglected to remove the sea cap on the gun’s muzzle. The gun exploded and killed the crew.

I too had my problems in this refinery. The refinery flare was often very large and always erratic. The gas being burned in the flare was plant fuel. The plant fuel was primarily cracked gas from the delayed coker, supplemented (as shown in Fig. 1-3) by vaporized LPG. So much fuel gas was lost by flaring that 90% of the Aruba’s LPG production had to be diverted to fuel, via the propane vaporizer.

I analyzed the problem based on the dynamics of the system. I modeled the refinery’s fuel consumption versus cracked gas production as a function of time. The key problem, based on my computer system dynamic analysis, was the cyclic production of cracked gas from the delayed coker complex. My report to Mr. English, the General Director of the Aruba Refinery, concluded:

1. The LPG vaporizer was responding too slowly to changes in cracked gas production from the delayed coker.
2. The natural log of the system time constants of the coker and vaporizer was out of synchronization.
3. A feed-forward, advanced computer control based on real-time dynamics would have to be developed to bring the coker vaporizer systems into dynamic real-time equilibrium.
4. A team of outside consultants, experts in this technology, should be contracted to provide this computer technology.

Six months passed. The complex, feed-forward computer system was integrated into the LPG makeup and flaring controls shown in Figure 1-3.
Adolf Hitler would have been more sympathetic than Mr. English. The refinery’s flaring continued just as before. Now what?

Distressed, discouraged, and dismayed, I went out to look at the vaporizer. I looked at the vaporizer for many hours. After a while I noticed that the fuel gas system pressure was dropping. This happened every 3 hours and was caused by the cyclic operation of the delayed coker. This was normal.

The falling fuel gas pressure caused the instrument air signal to the LPG makeup valve to increase. This was an “Air-to-Open” valve (see Chapter 13), and more air pressure was needed to open the propane flow control valve. This was normal.

But, the valve position itself did not move. The valve was stuck in a closed position. This was not normal.

You will understand that the operator in the control room was seeing the LPG propane makeup valve opening as the fuel gas pressure dropped. But the panel board operator was not really seeing the valve position; he was only seeing the instrument air signal to the valve.

Suddenly, the valve jerked open. The propane whistled through the valve. The local level indication in the vaporizer surged up, as did the fuel gas pressure. The flare valve opened to relieve the excess plant fuel gas pressure and remained open until the vaporizer liquid level sank back down, which took well over an hour. This all reminded me of the sticky side door to my garage in New Orleans.

I sprayed the control valve stem with WD-40, stroked the valve up and down with air pressure a dozen times, and cleaned the stem until it glistened. The next time the delayed coker cycled, the flow of LPG slowly increased to catch the falling fuel gas pressure, but without overshooting the pressure set point and initiating flaring.

Figure 1-3  Unintentional flaring caused by malfunction of LPG makeup control valve is an example of split-range pressure control
My mistake had been that I had assumed that the field instrumentation and control valves were working properly. I did not take into account the probability of a control valve malfunction. But at least I had learned from my mistake, which is more than you could say for Adolf Hitler.

LEARNING FROM THEORY

Northwestern University has an excellent postgraduate chemical engineering program. I know this because I was ejected from their faculty. I had been hired to present a course to their graduate engineers majoring in process control. My lecture began:

“Ladies and gentlemen, the thing you need to know about control theory is that if you try to get some place too fast, it’s hard to stop. Let’s look at Figure 1-4. In particular, let’s talk about tuning the reflux drum level control valve.

Do I want to keep the level in the drum close to 50%, or doesn’t it matter? As long as the level doesn’t get high enough to entrain light naphtha into fuel gas, that’s okay. What is not okay is to have an erratic flow feeding the light naphtha debutanizer tower.

On the other hand, if the overhead product was flowing into a large feed surge drum, than precise level control of the reflux drum is acceptable.

In order for the instrument technician to tune the level control valve, you have to show him what you want. To do this, put the level valve on manual. Next, manipulate the light naphtha flow to permit the level swings in the reflux drum you are willing to tolerate. But you will find that there is a problem. If you try to get back to the 50% level set point quickly, you will badly overshoot your level target.

Figure 1-4  Tuning a level control valve depends on what is downstream
If you return slowly to the set point, it’s easy to reestablish the 50% level target. However, the level will be off the target for a long time.

In conclusion, ladies and gentlemen, tuning a control loop is a compromise between the speed at which we wish to return to the set point and our tolerance to overshooting the target. To establish the correct tuning criteria, the control loop is best run on manual for a few hours by the Process Control Engineer. Thank you. Class adjourned for today.”

My students unfortunately adjourned to Dean Gold’s office. Dean Gold lectured me about the student’s complaints.

“Mr. Lieberman, did you think you were teaching a junior high school science class or a postgraduate course in process control?”

And I said, “Oh! Is there a difference?”
So that’s how I came to be ejected from the faculty of Northwestern University after my first day of teaching.

**LEARNING FROM RELATIONSHIPS**

My ex-girlfriend used to tell me, “Norm, the reason we get along so well is that I give you a lot of positive feedback.” From this I developed the impression that positive feedback is good. Which is true in a relationship with your girlfriend. But when involved in a relationship with a control loop, we want negative feedback. Control logic fails when in the positive feedback mode of control. For example:

- **Distillation**—As process engineers and operators we have the expectation that reflux improves fractionation, which is true, up to a point. That point where more reflux hurts fractionation instead of helps is called the “incipient flood point.” Beyond this point, the distillation tower is operating in a positive feedback mode of process control. That means the tray flooding reduces tray fractionation efficiency. More reflux simply makes the flooding worse.

- **Fired Heaters**—Increasing furnace fuel should increase the heater outlet temperature. But if the heat release is limited by combustion air, then increasing the fuel gas will reduce the heater outlet temperature. But as the heater outlet temperature drops, the automatic control calls for more fuel gas, which does not burn. As the heater outlet temperature continues to fall, because combustion is limited by air, the outlet temperature drops further. The heater automatic temperature control loop is now in the positive feedback mode of control. As long as this control loop is on auto, the problem will feed upon itself.
• **Vacuum Ejector**—Some refineries control vacuum tower pressure by controlling the motive steam flow to the steam ejector. As the steam pressure and flow to the ejector increases, the ejector pulls a better vacuum, as shown in Figure 1-5, but as the steam flow increases, so does that load on the downstream condenser. As the condenser becomes overloaded, the ejector discharge pressure rises. At some point the increased discharge pressure adversely affects the ejector’s suction pressure. A further increase in motive steam will make the vacuum worse, instead of better. As the vacuum gets worse, the control loop calls for more steam. Having now entered the positive feedback mode of control, the problem feeds upon itself.

Many control loops are subject to slipping into a positive feedback loop. The only way out of this trap is to switch the controls to manual and slowly climb back out of the trap. Once you guess (but there is no way to know for sure) that you are in the safe, negative feedback mode of control, you can then safely switch back to automatic control.

**NORMAL PURPOSE OF CONTROL LOOPS**

Typically, a control loop is tuned to achieve two objectives:

1. To return a variable to its set point as fast as possible.
2. To avoid overshooting the set point.
If a heater outlet set point is at 700°F, and it’s currently running at 680°F, the firing rate should increase. However, if the firing rate increases too fast, the heater outlet may jump past the set point to 720°F.

Tuning a control loop is meant to balance the instrument, “gain and reset,” to balance these two contradictory objectives.

The balance between gain and reset (i.e., instrument tuning) is not the main object of this text. Only rarely have I seen a panel board operator complain about this problem.

Another purpose of control is to optimize process variables. This is an advanced control that attempts to optimize certain variables. This is also not the sort of problem that the panel operator would be concerned about. An example of advanced control would be to optimize the ratios of several pumparound, versus the top reflux rate, for a refinery crude distillation tower. For the units I work on, such advanced computer control is rarely used, or has been simplified, so that it is not much different than ordinary closed-loop control.

**MANUAL VERSUS AUTO**

In reality, the main complaint about control loops that are communicated to me by operators is that the controller will not work in the automatic mode of control, and that the operators are forced to run the control loop in manual. This greatly increases and complicates their work.

To a large extent, this text examines why control loops are forced to run in the manual mode. A few of the reasons are the following:

1. The control loop is trapped in a “positive feedback loop.” This is often a dangerous situation.
2. There is no direct relationship between the variable being controlled and the response of the control valve. This is typically a design error.
3. The facility that measures the process parameter in the field is not working correctly. This represents the majority of control problems that I have seen.
4. The bypass valve is open around the control valve.
5. The control valve is running too far closed because it is oversized, or badly eroded.
6. The control valve is running too far open, because it is too small, or its port size is too small, or an isolation gate valve in the system is partly closed.
7. The control valve’s “Hand Jack” has been left engaged. Thus, the control valve cannot be manipulated from the computer console or panel. The hand jack is a mechanical device, used to manually move the control valve in the field.
8. The control valve is stuck in a fixed position.
9. The air signal connection to the diaphragm that moves the control valve has come loose.

10. The diaphragm is leaking, so the sufficient instrument air pressure cannot be applied to the control valve mechanism to force it to move.

**PROCESS CONTROL NOMENCLATURE**

The reader who is new to process plant vocabulary may wish to briefly skip to the glossary at the end of this book. I have assembled a list of “Process Control Nomenclature Used in Petroleum Refineries and Petrochemical Plants.” As in any other industry, your coworkers will have developed a vocabulary of their own, and will assume you understand the terms they employ. To an extent, in the following chapters of this text, I have also made a similar assumption.

A brief review of these terms may make it easier for you to communicate with some of your coworkers.