2.4.3 Decreasing Applied Field 44
2.5 Model Identification: Interpolation 46
2.6 Model Identification: Curve Fitting 47
2.7 The Congruency and the Deletion Properties 49
2.8 Conclusions 51
References 51

Chapter 3 Irreversible and Locally Reversible Magnetization 53
3.1 Introduction 53
3.2 State-Independent Reversible Magnetization 53
3.3 Magnetization-Dependent Reversible Model 55
3.4 State-Dependent Reversible Model 58
3.5 Energy Considerations 62
3.5.1 Hysteron Assemblies 64
3.6 Identification of Model Parameters 66
3.7 Apparent Reversible Magnetization 67
3.8 Crossover Condition 71
3.9 Conclusions 73
References 73

Chapter 4 The Moving Model and the Product Model 75
4.1 Introduction 75
4.2 Hard Materials 75
4.3 Identification of the Moving Model 80
4.3.1 The Symmetry Method 80
4.3.2 The Method of Tails 84
4.4 The Variable-Variance Model 86
4.5 Soft Materials 92
4.6 Henkel Plots 93
4.7 Congruency Property 95
4.7.1 The Classical Preisach Model 97
4.7.2 Output-Dependent Models 97
4.8 Deletion Property 100
4.8.1 Hysteresis in Intrinsically Nonhysteretic Materials 102
4.8.2 Proof of the Deletion Property 104
4.9 Conclusions 107
References 108
Chapter 5  Aftereffect and Accommodation  111
5.1 Introduction  111
5.2 Aftereffect  112
5.3 Preisach Interpretation of Aftereffect  120
5.4 Aftereffect Dependence on Magnetization History  123
5.5 Accommodation  125
5.6 Identification of Accommodation Parameters  134
5.7 Properties of Accommodation Models  137
  5.7.1 Types of Accommodation Processes  139
5.8 Deletion Property  143
5.9 Conclusions  144
References  144

Chapter 6  Vector Models  147
6.1 Introduction  147
6.2 General Properties of Vector Models  148
6.3 The Mayergoyz Vector Model  151
6.4 Pseudoparticle Models  152
6.5 Coupled-Hysteron Models  154
  6.5.1 Selection Rules  154
  6.5.2 The $m^2$ Model  158
  6.5.3 The Simplified Vector Model or SVM Model  159
6.6 Loss Properties  164
6.7 Conclusions  165
References  165

Chapter 7  Preisach Applications  167
7.1 Introduction  167
7.2 Dynamic Effects  167
7.3 Eddy Currents  168
7.4 Frequency Response of the Recording Process  170
7.5 Pulsed Behavior  172
  7.5.1 Dynamic Accommodation Model  173
  7.5.2 Single-Pulse Simulation  178
  7.5.3 Double-Pulse Simulation  181
7.6 Noise  181
  7.6.1 The Magnetization Model  183