

Contents

About the Authors	xiii
Preface	xv
Acknowledgements	xix
List of Symbols	xxi
PART I INTRODUCTION TO POWER SYSTEMS	
1 Introduction	3
1.1 Stability and Control of a Dynamic System	3
1.2 Classification of Power System Dynamics	5
1.3 Two Pairs of Important Quantities: Reactive Power/Voltage and Real Power/Frequency	7
1.4 Stability of a Power System	9
1.5 Security of a Power System	9
1.6 Brief Historical Overview	12
2 Power System Components	15
2.1 Introduction	15
2.1.1 <i>Reliability of Supply</i>	15
2.1.2 <i>Supplying Electrical Energy of Good Quality</i>	16
2.1.3 <i>Economic Generation and Transmission</i>	16
2.1.4 <i>Environmental Issues</i>	16
2.2 Structure of the Electrical Power System	16
2.2.1 <i>Generation</i>	18
2.2.2 <i>Transmission</i>	18
2.2.3 <i>Distribution</i>	19
2.2.4 <i>Demand</i>	19
2.3 Generating Units	19
2.3.1 <i>Synchronous Generators</i>	20
2.3.2 <i>Exciters and Automatic Voltage Regulators</i>	21
2.3.3 <i>Turbines and their Governing Systems</i>	25
2.4 Substations	35
2.5 Transmission and Distribution Network	35
2.5.1 <i>Overhead Lines and Underground Cables</i>	35
2.5.2 <i>Transformers</i>	36
2.5.3 <i>Shunt and Series Elements</i>	41
2.5.4 <i>FACTS Devices</i>	43

2.6	Protection	54
2.6.1	<i>Protection of Transmission Lines</i>	54
2.6.2	<i>Protection of Transformers</i>	56
2.6.3	<i>Protection of Busbars</i>	57
2.6.4	<i>Protection of Generating Units</i>	57
2.7	Wide Area Measurement Systems	58
2.7.1	<i>WAMS and WAMPAC Based on GPS Signal</i>	58
2.7.2	<i>Phasors</i>	59
2.7.3	<i>Phasor Measurement Unit</i>	61
2.7.4	<i>Structures of WAMS and WAMPAC</i>	62
3	The Power System in the Steady State	65
3.1	Transmission Lines	65
3.1.1	<i>Line Equations and the π-Equivalent Circuit</i>	66
3.1.2	<i>Performance of the Transmission Line</i>	67
3.1.3	<i>Underground Cables</i>	72
3.2	Transformers	72
3.2.1	<i>Equivalent Circuit</i>	72
3.2.2	<i>Off-Nominal Transformation Ratio</i>	74
3.3	Synchronous Generators	76
3.3.1	<i>Round-Rotor Machines</i>	76
3.3.2	<i>Salient-Pole Machines</i>	83
3.3.3	<i>Synchronous Generator as a Power Source</i>	89
3.3.4	<i>Reactive Power Capability Curve of a Round-Rotor Generator</i>	91
3.3.5	<i>Voltage–Reactive Power Capability Characteristic $V(Q)$</i>	95
3.3.6	<i>Including the Equivalent Network Impedance</i>	100
3.4	Power System Loads	104
3.4.1	<i>Lighting and Heating</i>	105
3.4.2	<i>Induction Motors</i>	106
3.4.3	<i>Static Characteristics of the Load</i>	110
3.4.4	<i>Load Models</i>	111
3.5	Network Equations	113
3.6	Power Flows in Transmission Networks	118
3.6.1	<i>Control of Power Flows</i>	118
3.6.2	<i>Calculation of Power Flows</i>	122

PART II INTRODUCTION TO POWER SYSTEM DYNAMICS

4	Electromagnetic Phenomena	127
4.1	Fundamentals	127
4.2	Three-Phase Short Circuit on a Synchronous Generator	129
4.2.1	<i>Three-Phase Short Circuit with the Generator on No Load and Winding Resistance Neglected</i>	129
4.2.2	<i>Including the Effect of Winding Resistance</i>	133
4.2.3	<i>Armature Flux Paths and the Equivalent Reactances</i>	134
4.2.4	<i>Generator Electromotive Forces and Equivalent Circuits</i>	140
4.2.5	<i>Short-Circuit Currents with the Generator Initially on No Load</i>	146
4.2.6	<i>Short-Circuit Currents in the Loaded Generator</i>	149
4.2.7	<i>Subtransient Torque</i>	150

Contents	vii
4.3 Phase-to-Phase Short Circuit	152
4.3.1 <i>Short-Circuit Current and Flux with Winding Resistance Neglected</i>	153
4.3.2 <i>Influence of the Subtransient Saliency</i>	156
4.3.3 <i>Positive- and Negative-Sequence Reactances</i>	159
4.3.4 <i>Influence of Winding Resistance</i>	160
4.3.5 <i>Subtransient Torque</i>	162
4.4 Synchronization	163
4.4.1 <i>Currents and Torques</i>	164
4.5 Short-Circuit in a Network and its Clearing	166
5 Electromechanical Dynamics – Small Disturbances	169
5.1 Swing Equation	169
5.2 Damping Power	172
5.2.1 <i>Damping Power at Large Speed Deviations</i>	175
5.3 Equilibrium Points	176
5.4 Steady-State Stability of Unregulated System	177
5.4.1 <i>Pull-Out Power</i>	177
5.4.2 <i>Transient Power–Angle Characteristics</i>	179
5.4.3 <i>Rotor Swings and Equal Area Criterion</i>	184
5.4.4 <i>Effect of Damper Windings</i>	186
5.4.5 <i>Effect of Rotor Flux Linkage Variation</i>	187
5.4.6 <i>Analysis of Rotor Swings Around the Equilibrium Point</i>	191
5.4.7 <i>Mechanical Analogues of the Generator–Infinite Busbar System</i>	195
5.5 Steady-State Stability of the Regulated System	196
5.5.1 <i>Steady-State Power–Angle Characteristic of Regulated Generator</i>	196
5.5.2 <i>Transient Power–Angle Characteristic of the Regulated Generator</i>	200
5.5.3 <i>Effect of Rotor Flux Linkage Variation</i>	202
5.5.4 <i>Effect of AVR Action on the Damper Windings</i>	205
5.5.5 <i>Compensating the Negative Damping Components</i>	206
6 Electromechanical Dynamics – Large Disturbances	207
6.1 Transient Stability	207
6.1.1 <i>Fault Cleared Without a Change in the Equivalent Network Impedance</i>	207
6.1.2 <i>Short-Circuit Cleared with/without Auto-Reclosing</i>	212
6.1.3 <i>Power Swings</i>	215
6.1.4 <i>Effect of Flux Decrement</i>	215
6.1.5 <i>Effect of the AVR</i>	216
6.2 Swings in Multi-Machine Systems	220
6.3 Direct Method for Stability Assessment	222
6.3.1 <i>Mathematical Background</i>	223
6.3.2 <i>Energy-Type Lyapunov Function</i>	225
6.3.3 <i>Transient Stability Area</i>	227
6.3.4 <i>Equal Area Criterion</i>	228
6.3.5 <i>Lyapunov Direct Method for a Multi-Machine System</i>	230
6.4 Synchronization	237
6.5 Asynchronous Operation and Resynchronization	239
6.5.1 <i>Transition to Asynchronous Operation</i>	240
6.5.2 <i>Asynchronous Operation</i>	241
6.5.3 <i>Possibility of Resynchronization</i>	242

6.6	Out-of-Step Protection Systems	244
6.6.1	<i>Impedance Loci During Power Swings</i>	245
6.6.2	<i>Power Swing Blocking</i>	248
6.6.3	<i>Pole-Slip Protection of Synchronous Generator</i>	249
6.6.4	<i>Out-of-Step Tripping in a Network</i>	251
6.6.5	<i>Example of a Blackout</i>	253
6.7	Torsional Oscillations in the Drive Shaft	253
6.7.1	<i>The Torsional Natural Frequencies of the Turbine–Generator Rotor</i>	253
6.7.2	<i>Effect of System Faults</i>	259
6.7.3	<i>Subsynchronous Resonance</i>	261
7	Wind Power	265
7.1	Wind Turbines	265
7.1.1	<i>Generator Systems</i>	269
7.2	Induction Machine Equivalent Circuit	274
7.3	Induction Generator Coupled to the Grid	277
7.4	Induction Generators with Slightly Increased Speed Range via External Rotor Resistance	280
7.5	Induction Generators with Significantly Increased Speed Range: DFIGs	282
7.5.1	<i>Operation with the Injected Voltage in Phase with the Rotor Current</i>	284
7.5.2	<i>Operation with the Injected Voltage out of Phase with the Rotor Current</i>	286
7.5.3	<i>The DFIG as a Synchronous Generator</i>	287
7.5.4	<i>Control Strategy for a DFIG</i>	289
7.6	Fully Rated Converter Systems: Wide Speed Control	290
7.6.1	<i>Machine-Side Inverter</i>	291
7.6.2	<i>Grid-Side Inverter</i>	292
7.7	Peak Power Tracking of Variable Speed Wind Turbines	293
7.8	Connections of Wind Farms	294
7.9	Fault Behaviour of Induction Generators	294
7.9.1	<i>Fixed-Speed Induction Generators</i>	294
7.9.2	<i>Variable-Speed Induction Generators</i>	296
7.10	Influence of Wind Generators on Power System Stability	296
8	Voltage Stability	299
8.1	Network Feasibility	299
8.1.1	<i>Ideally Stiff Load</i>	300
8.1.2	<i>Influence of the Load Characteristics</i>	303
8.2	Stability Criteria	305
8.2.1	<i>The $d\Delta Q/dV$ Criterion</i>	305
8.2.2	<i>The dE/dV Criterion</i>	308
8.2.3	<i>The dQ_G/dQ_L Criterion</i>	309
8.3	Critical Load Demand and Voltage Collapse	310
8.3.1	<i>Effects of Increasing Demand</i>	311
8.3.2	<i>Effect of Network Outages</i>	314
8.3.3	<i>Influence of the Shape of the Load Characteristics</i>	315
8.3.4	<i>Influence of the Voltage Control</i>	317
8.4	Static Analysis	318
8.4.1	<i>Voltage Stability and Load Flow</i>	318
8.4.2	<i>Voltage Stability Indices</i>	320

Contents	ix
8.5 Dynamic Analysis	321
8.5.1 <i>The Dynamics of Voltage Collapse</i>	321
8.5.2 <i>Examples of Power System Blackouts</i>	323
8.5.3 <i>Computer Simulation of Voltage Collapse</i>	326
8.6 Prevention of Voltage Collapse	327
8.7 Self-Excitation of a Generator Operating on a Capacitive Load	329
8.7.1 <i>Parametric Resonance in RLC Circuits</i>	329
8.7.2 <i>Self-Excitation of a Generator with Open-Circuited Field Winding</i>	330
8.7.3 <i>Self-Excitation of a Generator with Closed Field Winding</i>	332
8.7.4 <i>Practical Possibility of Self-Excitation</i>	334
9 Frequency Stability and Control	335
9.1 Automatic Generation Control	336
9.1.1 <i>Generation Characteristic</i>	336
9.1.2 <i>Primary Control</i>	339
9.1.3 <i>Secondary Control</i>	341
9.1.4 <i>Tertiary Control</i>	345
9.1.5 <i>AGC as a Multi-Level Control</i>	346
9.1.6 <i>Defence Plan Against Frequency Instability</i>	347
9.1.7 <i>Quality Assessment of Frequency Control</i>	349
9.2 Stage I – Rotor Swings in the Generators	350
9.3 Stage II – Frequency Drop	353
9.4 Stage III – Primary Control	354
9.4.1 <i>The Importance of the Spinning Reserve</i>	356
9.4.2 <i>Frequency Collapse</i>	358
9.4.3 <i>Underfrequency Load Shedding</i>	360
9.5 Stage IV – Secondary Control	360
9.5.1 <i>Islanded Systems</i>	361
9.5.2 <i>Interconnected Systems and Tie-Line Oscillations</i>	364
9.6 FACTS Devices in Tie-Lines	370
9.6.1 <i>Incremental Model of a Multi-Machine System</i>	371
9.6.2 <i>State-Variable Control Based on Lyapunov Method</i>	375
9.6.3 <i>Example of Simulation Results</i>	378
9.6.4 <i>Coordination Between AGC and Series FACTS Devices in Tie-Lines</i>	379
10 Stability Enhancement	383
10.1 Power System Stabilizers	383
10.1.1 <i>PSS Applied to the Excitation System</i>	384
10.1.2 <i>PSS Applied to the Turbine Governor</i>	387
10.2 Fast Valving	387
10.3 Braking Resistors	391
10.4 Generator Tripping	392
10.4.1 <i>Preventive Tripping</i>	393
10.4.2 <i>Restitutive Tripping</i>	394
10.5 Shunt FACTS Devices	395
10.5.1 <i>Power–Angle Characteristic</i>	395
10.5.2 <i>State-Variable Control</i>	397
10.5.3 <i>Control Based on Local Measurements</i>	400
10.5.4 <i>Examples of Controllable Shunt Elements</i>	404
10.5.5 <i>Generalization to Multi-Machine Systems</i>	406
10.5.6 <i>Example of Simulation Results</i>	414

10.6 Series Compensators	416
10.6.1 State-Variable Control	417
10.6.2 Interpretation Using the Equal Area Criterion	419
10.6.3 Control Strategy Based on the Squared Current	420
10.6.4 Control Based on Other Local Measurements	421
10.6.5 Simulation Results	423
10.7 Unified Power Flow Controller	423
10.7.1 Power–Angle Characteristic	424
10.7.2 State-Variable Control	426
10.7.3 Control Based on Local Measurements	428
10.7.4 Examples of Simulation Results	429

PART III ADVANCED TOPICS IN POWER SYSTEM DYNAMICS

11 Advanced Power System Modelling	433
11.1 Synchronous Generator	433
11.1.1 Assumptions	434
11.1.2 The Flux Linkage Equations in the Stator Reference Frame	434
11.1.3 The Flux Linkage Equations in the Rotor Reference Frame	436
11.1.4 Voltage Equations	440
11.1.5 Generator Reactances in Terms of Circuit Quantities	443
11.1.6 Synchronous Generator Equations	446
11.1.7 Synchronous Generator Models	453
11.1.8 Saturation Effects	458
11.2 Excitation Systems	462
11.2.1 Transducer and Comparator Model	462
11.2.2 Exciters and Regulators	463
11.2.3 Power System Stabilizer (PSS)	470
11.3 Turbines and Turbine Governors	470
11.3.1 Steam Turbines	471
11.3.2 Hydraulic Turbines	476
11.3.3 Wind Turbines	481
11.4 Dynamic Load Models	485
11.5 FACTS Devices	488
11.5.1 Shunt FACTS Devices	488
11.5.2 Series FACTS Devices	488
12 Steady-State Stability of Multi-Machine System	491
12.1 Mathematical Background	491
12.1.1 Eigenvalues and Eigenvectors	491
12.1.2 Diagonalization of a Square Real Matrix	496
12.1.3 Solution of Matrix Differential Equations	500
12.1.4 Modal and Sensitivity Analysis	509
12.1.5 Modal Form of the State Equation with Inputs	512
12.1.6 Nonlinear System	513
12.2 Steady-State Stability of Unregulated System	514
12.2.1 State-Space Equation	515
12.2.2 Simplified Steady-State Stability Conditions	517
12.2.3 Including the Voltage Characteristics of the Loads	521
12.2.4 Transfer Capability of the Network	522

Contents	xi
12.3 Steady-State Stability of the Regulated System	523
12.3.1 <i>Generator and Network</i>	523
12.3.2 <i>Including Excitation System Model and Voltage Control</i>	525
12.3.3 <i>Linear State Equation of the System</i>	528
12.3.4 <i>Examples</i>	528
13 Power System Dynamic Simulation	535
13.1 Numerical Integration Methods	536
13.2 The Partitioned Solution	541
13.2.1 <i>Partial Matrix Inversion</i>	543
13.2.2 <i>Matrix Factorization</i>	547
13.2.3 <i>Newton's Method</i>	548
13.2.4 <i>Ways of Avoiding Iterations and Multiple Network Solutions</i>	551
13.3 The Simultaneous Solution Methods	553
13.4 Comparison Between the Methods	554
14 Power System Model Reduction – Equivalents	557
14.1 Types of Equivalents	557
14.2 Network Transformation	559
14.2.1 <i>Elimination of Nodes</i>	559
14.2.2 <i>Aggregation of Nodes Using Dima's Method</i>	562
14.2.3 <i>Aggregation of Nodes Using Zhukov's Method</i>	563
14.2.4 <i>Coherency</i>	565
14.3 Aggregation of Generating Units	567
14.4 Equivalent Model of External Subsystem	568
14.5 Coherency Recognition	569
14.6 Properties of Coherency-Based Equivalents	573
14.6.1 <i>Electrical Interpretation of Zhukov's Aggregation</i>	573
14.6.2 <i>Incremental Equivalent Model</i>	575
14.6.3 <i>Modal Interpretation of Exact Coherency</i>	579
14.6.4 <i>Eigenvalues and Eigenvectors of the Equivalent Model</i>	582
14.6.5 <i>Equilibrium Points of the Equivalent Model</i>	589
Appendix	593
References	613
Index	623

