

Index

- Absorber
 - tuned, 146, 148
 - vibration, 24, 145, 146
- Accelerometer, 224
- Active control, 25, 158
- Actuator, 25, 27
- Actuator dynamics, 345, 353
- Adjoint boundary conditions, 300, 301
- Adjoint operator, 299
- Admittance matrix, 354
- Aliasing, 226, 227
- Almost everywhere function, 292
- Amplitude, 146, 224
- Analysis
 - design sensitivity, 155
 - functional, 312, 361
 - modal
 - complex exponential method, 235
 - eigensystem realization analysis (ERA), 238, 240, 244
 - experimental (EMA), 221, 232
 - time domain method, 235, 238, 244
 - substructure, 342
- Analyzer, 225–226, 228, 231, 232
- Antialiasing filter, 227
- Apparent mass, 15
- Appended boundaries, 258, 262
- Argand plane plot, 17
- Assumed mode method, 336
- Asymmetric matrix, 47, 90
- Asymmetric system, 109
- Asymptotically stable system, 22, 100–101, 103–104, 107
- Asymptotic stability, 103–104, 117
- Asymptotic state estimator, 186
- Autocorrelation function, 230–231
- Auxiliary problem, 284–285
- Average signal, 230
- Balanced system
 - internally, 195
- Banach space, 294
- Bandwidth, 11
- Basis, 60, 66
- Beam equations
 - Euler–Bernoulli, 261
 - Timoshenko, 260, 261
- Beam vibration
 - layered, 268
- Bessel's inequality, 296
- BIBO stability, 135–136
- Biharmonic operator, 267
- Biorthogonality, 71
- Block diagram, 16
- Bode magnitude plot, 18
- Bode phase plot, 18
- Bode plot, 17, 18
- Boundary(ies)
 - appended, 257, 258, 262
 - divergence, 119
 - flutter, 119
 - stability, 118–119
- Boundary conditions
 - adjoint, 300, 301
 - geometric, 270, 335
 - natural, 270, 335
- Boundary control
 - bounded function, 134, 299
 - bounded-input, bounded-output stability (BIBO), 23, 134, 138
- Bounded operator, 299–300, 303

- Bounded sequence, 303
- Bounded stability, 135

- Canonical forms, 71
- Cauchy sequence, 294
- Characteristic equation, 5, 60, 252
- Characteristic roots, 57
- Characteristic values, 22, 74, 253
- Circle fit method, 235
- Circulatory matrix, 42, 108
- Circulatory system, 43, 107–108
- Closed-loop control, 25, 26, 27
- Closed-loop stability, 115
- Closed-loop system, 25, 27, 169, 171
- Coefficient(s)
 - digital spectral, 227
 - Fourier, 225, 296, 304, 323
 - influence
 - damping, 52
 - flexibility, 51
 - inertial, 51
 - stiffness, 50–51
 - matrix, 41, 47, 57, 138, 344
 - modal input, 347
 - spectral, 225, 227–228
 - undetermined, method of, 9, 158
- Coercive operator, 306
- Coherence function, 232
- Column rank, 361
- Combined dynamical system, 320
- Compact operator, 303
- Completely continuous operator, 303
- Completely state controllable
 - system, 172
- Completeness, 254, 294
- Complete set, 296
- Complete space, 296
- Complex conjugate transpose, 62
- Complex modulus, 324, 325
- Complex stiffness
 - Kimball–Lovell, 325
- Compliance, 15, 17
- Condensation
 - mass, 163
- Conjugate transpose, 62, 65, 349
- Connecting nodes, 343
- Conservative system
 - gyroscopic, 43
 - nongyroscopic
 - undamped, 63, 128
 - stability, 101
- Consistent mass matrix, 340
- Constant
 - modal, 139, 234
 - of proportionality, 5, 50–52
 - time, 160
- Constraint damping, 43
- Constraint damping matrix, 42, 43
- Continuous function, 285, 287, 295, 303
- Continuous operator, 303
- Control
 - active, 158–160
 - boundary, 328
 - closed-loop, 25, 26, 27, 169
 - distributed parameter system, 345–352
 - feedback, 44–49
 - output, 189–190
 - stability, 113–116
 - of states, 26, 44, 175
 - gain, 26
 - ideal, 200
 - independent, 202, 203, 206
 - modal, 198–201, 202–206, 326–328
 - modal pole placement, 202
 - nonmodal distributed, 328–329
 - open-loop, 25
 - optimal, 179–185
 - passive, 158–160
 - structural, 169
 - vibration, 24, 180, 325
- Controllability
 - modal, 330
- Controllability grammian, 193
- Controllability matrix, 172
- Controllability norm, 174
- Control law, 25, 170
- Control methods
 - modal, 198–199, 208, 326
- Control spillover, 201, 352
- Control system
 - feedback, 44–49
- Control vector, 170
- Convergence
 - norm, 294
 - strong, 294
- Coordinate(s)
 - decoupled, 130, 133, 201
 - modal, 130, 134, 199, 202
 - natural, 130
 - normal, 130, 136
 - vector, 128
- Cost function, 148, 149, 152
- Courant minimax principle, 307
- Critical damping curve, 81
- Critically damped response, 8
- Critically damped structure, 7–8, 310
- Critically damped system, 8, 77
- Cross-correlation function, 231
- Cross-spectral density, 231
- Curve(s)
 - critical damping, 81
 - magnification, 11, 12, 233
 - transmissibility, 146, 147

- Damped gyroscopic system, 106–107
- Damped membrane equation, 270
- Damped natural frequency, 6, 233
- Damped nongyroscopic system, 43

- Damped plate equation, 270
- Damped structure
 - critically, 7–8, 310
 - mixed, 311
- Damped system
 - critically, , 8, 77
 - pervasively, 107
 - stability, 22–24
- Damper, 4–8, 9
- Damping
 - constraint, 43, 71
 - extensional, 325
 - external, 43, 271
 - internal, 50, 271
 - layer
 - free, 325
 - unconstrained, 325
 - mixed, 78, 311, 317
 - Rayleigh, 75
 - semidefinite, 103–104, 107
 - viscous, 270–271
- Damping curve
 - critical, 81
- Damping influence coefficient, 52
- Damping matrix, 42, 52, 75, 81, 103, 155
- Damping operator, 271
- Damping ratio(s)
 - modal, 76, 139, 154, 155
- Damping ratio matrix, 153
- Dashpot, 5, 80, 145
- Decade, 18, 222
- Decay envelope, 19
- Decay rate, 160
- Decibel, 18, 359
- Decoupled coordinates, 130, 204
- Decrement
 - logarithmic, 19, 20, 160
- Definiteness of a matrix, 42, 46, 78
- Deflection
 - static, 2
- Degeneracy, 73
- Degenerate eigenvector, 119
- Degenerate lambda matrix, 75, 119
- Delta
 - Kronecker, 61, 62
- Delta function
 - Dirac, 12, 285, 317
- Density
 - cross-spectral, 231
- Dependent eigenvector, 58, 71, 104
- Dependent vectors, 60, 69
- Design
 - modal, 318–319
 - vibration, 66, 148, 357
- Design sensitivity, 155–157
- Determinant
 - matrix, 59, 279
- DFT, 225
- Diagonal matrix, 61–62, 71–72, 153, 199
- Digital Fourier transform (DFT), 225, 227, 228, 238
- Digital spectral coefficients, 227
- Dimension
 - matrix, 40, 135, 202, 353
- Dirac delta function, 12, 285
- Direct method of Lyapunov, 103, 105, 328
- Discriminant, 5, 310
- Displacement
 - initial, 3, 41, 131, 255
- Displacement vector
 - nodal, 47, 162, 339
- Distributed control
 - nonmodal, 328–329
- Distributed parameter system, 271
- Divergence boundary, 119
- Divergent instability, 22, 23
- Domain, 235–241
- Dot product, 40, 60
- Driving forces, 23, 223
- Driving frequency, 17, 136
- Dynamic stiffness, 15
- Dynamic stiffness matrix, 353
- Eigenfunction(s)
 - of a beam, 253, 276, 280, 354
 - normalized, 278, 280
 - orthonormal, 303, 306
- Eigenfunction expansion, 278, 299, 303
- Eigensolution
 - sensitivity, 155, 157, 240, 320
- Eigenstructure, 177, 179, 254, 303
- Eigenstructure assignment, 176–179
- Eigensystem realization algorithm (ERA), 238, 240, 244
- Eigenvalue(s)
 - of a beam, 277, 280
 - estimation of, 81–88, 306–307
 - inequalities for, 83
 - invariant, 61
 - of a matrix, 63
 - membrane, 309
 - of a system, 83, 84, 101, 237, 253
- Eigenvalue placement, 158
- Eigenvalue problem
 - matrix, 57, 58, 323
- Eigenvector(s)
 - degenerate, 119
 - dependent, 69, 72, 235
 - left, 71, 87
 - of a matrix, 58, 61, 62, 64, 66, 75, 76, 103
 - normalized, 62, 70, 76, 130, 157, 196
 - perturbation of, 87, 93, 155
 - right, 71, 75, 95
 - of a system, 128, 235
- Elastic restoring forces, 1
- Electromagnetic shaker, 223
- Element stiffness matrix, 339
- EMA, 221
- Enclosure theorems, 308–309

- Envelope
 - decay, 19
- Equality, 297, 309
- Equation
 - beam
 - characteristic, 321, 323
 - damped membrane, 270
 - damped plate, 270
 - Euler–Bernoulli, 261
 - Lagrange’s, 40, 338
 - linear, 88, 117, 205, 223, 228, 362, 542
 - Lyapunov, 116, 184
 - nonlinear, 52
 - Riccati, 181
 - Timoshenko, 256, 257, 260
- Equilibrium
 - stable, 99, 103
- ERA, 238
- Error matrix, 84
- Estimate
 - eigenvalue, 81–88, 306–307
 - natural frequency, 2, 17, 21, 25, 65, 81, 209, 222, 233, 317
- Estimated state vector, 186, 189
- Estimator
 - asymptotic state, 186
 - open-loop, 186
- Euler–Bernoulli beam equations, 261
- Euler’s formulas, 4, 67, 102
- Excitation frequency, 10
- Expansion theorem, 69, 296–297
- Experimental modal analysis (EMA), 138, 142, 221, 232
- Extensional damping, 325
- External damping, 43, 270–271
- External forces, 41, 43

- Fast Fourier transform (FFT), 225, 228
- Feedback
 - output, 114, 170, 176, 177, 346, 350
 - position, 208–211
 - state, 26, 44, 175, 176, 186, 190, 346
 - state variable, 170, 176, 202
 - velocity, 44, 49, 170, 177, 202, 204
- Feedback control
 - output, 25, 189, 346, 350
 - stability, 113–116
 - of states, 44, 346
- Feedback control system, 44–49
- Feedback gain matrix, 175, 176
- FEM, 337
- FFT, 225, 228
- Filter(s)
 - antialiasing, 227
 - Kalman, 190
- Finite element, 161–162
- Finite element method (FEM), 337–342
- First mode shape, 68
- Flexibility influence coefficient, 51
- Flutter boundary, 119
- Flutter instability, 22
- Follower force, 48
- Force(s)
 - driving, 9, 14, 23, 137, 146, 147, 222, 223, 233
 - elastic restoring, 1
 - external, 8, 41, 43, 123, 136
 - follower, 48
- Forced response
 - stability, 23, 134–136
- Force vector
 - nodal, 339
- Formally self-adjoint operator, 300
- Fourier coefficient, 225, 296, 304
- Fourier series, 225, 254, 296
- Fourier transform
 - digital (DFT), 225, 228, 238
 - fast, 225, 228
- Free layer damping, 325
- Frequency(ies)
 - of applied force, 9
 - driving, 9, 11, 17, 49, 81, 136, 147
 - excitation, 10
 - modal, 76, 91, 204
 - natural
 - damped, 6, 75
 - sensitivity, 155
 - undamped, 76, 137, 316, 317
 - Nyquist, 227
- Frequency domain methods, 14, 235, 238
- Frequency methods, 14–19
- Frequency response, 16–17, 20, 138–140, 232–233
- Frequency response function (FRF), 16, 17, 233
- Frequency of vibration
 - natural, 63
- FRF, 16
- Function(s)
 - almost everywhere, 292, 293
 - autocorrelation, 230–231
 - bounded, 254
 - coherence, 232
 - continuous, 285, 303
 - cost, 148, 152, 180, 185
 - cross-correlation, 231
 - Dirac delta, 12, 285, 317
 - frequency response (FRF), 16, 17, 21, 233
 - Green’s, 284–288, 321
 - influence, 285
 - interpolation, 339
 - Lyapunov, 101, 328
 - objective, 148, 149, 151
 - piecewise continuous, 254, 287
 - shape, 339, 342
 - square integrable, 292
 - step, 12, 13, 24
 - transfer, 14–19, 191
 - unit impulse, 12
 - window, 228
- Functional analysis, 306

- Gain, 26, 44, 175, 178
- Gain control, 26
- Generalized Hankel matrix, 239
- Generalized infinite matrix, 323
- Generalized inverse
 - left, 177
 - right, 178
- Geometric boundary conditions, 270, 335
- Gerschgorin circles, 85
- Global stiffness matrix, 342
- Grammian
 - controllability, 193
 - observability, 193, 197
- Greatest lower bound, 306
- Green's function, 284–288, 321
- Grid, 338
- Guyan reduction, 164
- Gyroscope, 43, 47
- Gyroscopic matrix, 42
- Gyroscopic system
 - conservative, 47, 106
 - damped, 106–107
 - stability, 104–106
 - undamped, 43, 104, 107

- Half-power points, 21, 233
- Hammer
 - impact, 223–224
 - impulse, 12
- Hankel matrix, 239, 240
- Hanning window, 228, 229
- Harmonic motion
 - simple, 1
- Hilbert space
 - separable, 295
- Homogeneous solution, 9, 123, 133
- Hurwitz matrix, 117, 118
- Hurwitz test, 117
- Hybrid system, 320

- Ibrahim time domain (ITD)
 - method, 235
- Ideal control, 200
- Identity matrix, 42, 44, 125, 240, 349
- Impact hammer, 223, 224
- Impedance
 - modal, 346
- Impedance matrix, 348, 350
- Impulse function
 - unit, 12
- Impulse hammer, 223
- Impulse response, 13
- Inconsistent mass matrix, 162, 340
- Indefinite matrix, 42, 78, 81, 161
- Independent control, 202, 203, 206
- Independent vectors, 60
- Inertance, 15, 21
- Inertial influence coefficient, 51
- Inertia matrix, 41

- Infinite matrix
 - generalized, 323
- Influence coefficient(s)
 - damping, 52
 - flexibility, 51
 - inertial, 51
 - stiffness, 50
- Influence function, 285
- Initial displacement, 3, 41, 131, 255
- Initial velocity, 3, 6, 13
- Inner product, 40, 292–293, 295
- Input coefficients
 - modal, 347
- Input matrix, 44, 45
- Instability
 - divergent, 22, 23
 - flutter, 22, 23, 119
- Integral operator, 287, 303
- Integration
 - Lebesgue, 292–293
 - Riemann, 291–292
- Internal damping, 50, 271
- Internally balanced system, 195
- Interpolation function, 339
- Invariance, 61, 73
- Invariant eigenvalues, 61
- Inverse
 - generalized
 - left, 177
 - right, 178
 - left, 362
 - matrix, 45
 - Moore–Penrose, 363
 - operator, 284, 287, 298
 - product of square matrices, 45
 - right, 362
- Inverse Laplace transform, 26, 124
- Inverse matrix, 353
- Inverse problem(s), 221, 222
- Irreducible realization, 191, 192
- ITD, 235

- Jordan's theorem, 72

- Kalman filters, 190
- Kimball–Lovell complex stiffness, 325
- Kronecker delta, 61, 62
- KTC theorem, 107, 110

- Lagrange multipliers, 148
- Lagrange's equations, 40, 338, 341, 344
- Lagrange stability, 135
- Lag value, 231
- Lambda matrix
 - degenerate, 75
 - simple, 75
- Laplace operator, 264

- Laplace transform
 - inverse, 26, 124, 191
- Latent roots, 74, 236
- Latent vector, 74–75
- Law
 - control, 25–26, 170, 176, 182
- Layer damping
 - free, 325
 - unconstrained, 325
- Layered beam vibrations, 268, 326
- Layered structure, 271, 325
- Leakage, 228
- Lebesgue integration, 292–293
- Left eigenvector, 71
- Left generalized inverse, 177
- Left inverse, 362
- Left singular vectors, 193
- Linear equation, 52, 88, 117, 205, 228
- Linear functional, 299
- Linear independence, 60, 292
- Linearly independent vectors, 60
- Linear regulator problem, 180, 181
- Linear space, 292, 293, 295
- Linear spring, 27, 28, 262
- Logarithmic decrement, 19–20, 160
- Longitudinal vibration, 256, 271, 285
- Loss factor, 12, 325
- Luenberger observer, 190
- Lumped-parameter system, 39, 123–142
- Lyapunov equation, 116, 184
- Lyapunov function, 101, 328
- Lyapunov stability, 99–101

- Magnification curve, 11, 12, 146, 233
- Magnification factor, 11
- Marginal stability, 120
- Markov parameters, 239
- Mass
 - apparent, 15
- Mass condensation, 163
- Mass loading, 223
- Mass matrix
 - consistent, 340
 - inconsistent, 162, 340
- Mass operator, 271
- Matrix(es)
 - addition, 59, 140
 - admittance, 354
 - asymmetric, 41, 90, 108
 - canonical, 71–23
 - circulatory, 42
 - column rank, 361
 - constraint damping, 42, 43, 71
 - controllability, 172
 - damping, 41, 42, 46, 81, 93, 153
 - damping ratio, 153
 - definiteness, 42, 46
 - determinant, 263
 - diagonal, 61–62, 71, 127
 - dimension, 39, 40, 135
 - eigenvalue, 57, 58, 64
 - eigenvector, 278
 - error, 84
 - feedback gain, 44, 175, 176, 179
 - generalized infinite, 323
 - generalized inverse, 177–178, 363
 - gyroscopic, 42
 - Hankel
 - generalized, 239
 - Hurwitz, 117
 - identity, 42, 44, 58, 62, 207, 362
 - impedance, 348, 350
 - indefinite, 42, 81, 117
 - inertia, 41
 - input, 44, 45, 190
 - inverse
 - Moore–Penrose, 363
 - lambda, 75–76, 133
 - mass
 - consistent, 340
 - inconsistent, 162, 340
 - modal, 75, 128, 133, 343
 - negative definite, 42, 104, 185
 - negative semidefinite, 42
 - nonnegative definite, 42
 - nonsingular, 61, 72, 191, 199
 - normal, 68, 75, 76, 130
 - null space, 103, 297
 - observability, 173, 174
 - orthogonal, 62, 70, 76, 130, 181, 193
 - orthogonally similar, 62
 - perturbation of, 86, 87, 206
 - positive definite, 42, 43, 46, 64, 89, 107, 112, 194
 - positive semidefinite, 42, 46, 117
 - principle minor, 66, 154
 - product of, 45, 78, 89, 108
 - pseudoinverse, 363
 - pseudosymmetric, 108, 109
 - rank, 60, 104, 110, 135, 193, 361
 - receptance, 138, 139, 140, 233, 241
 - residue, 139
 - resolvent, 124
 - Riccati, 181
 - row rank, 361
 - sign variable, 42
 - similar, 62
 - similarity transformation, 61, 71, 73, 164
 - singular, 91
 - skew symmetric, 41, 42, 43, 46
 - square, 40, 41, 58, 125, 177, 343
 - square root of, 64, 71, 89, 108
 - state, 44, 74, 90, 135, 196
 - state transition, 127
 - stiffness
 - dynamic, 15, 353
 - element, 339
 - global, 342

- symmetric, 41, 42, 65, 67, 71, 83, 84, 86, 156, 302, 362
- symmetrizable, 108
- times a scalar, 42, 58, 59
- trace, 73
- transpose, 41, 62, 108
- uncertainty in, 206, 207
- unperturbed, 86
- upper triangular, 72, 89
- viscous damping, 41
- weighting, 62, 180, 182, 214
- Matrix coefficients, 41, 52, 138
- Matrix eigenvalue problem, 57, 58, 323
- Matrix exponential, 125
- Matrix Riccati equation, 181
- MDOF system, 39
- Mean
 - signal, 230
- Mean square value
 - root, 229, 230
- Membrane
 - damped, 270
 - eigenvalue, 309
- Mesh, 338
- MIMO system, 192, 204
- Minimal realization, 191
- Minimum time problem, 180
- Mixed damped structure, 311
- Mixed damping, 78
- Mobility, 15, 17, 21
- Modal analysis
 - complex exponential method, 235
 - eigensystem realization algorithm (ERA), 238, 240, 244, 247
 - experimental (EMA), 221, 243
 - time domain method, 235, 238
- Modal analysis techniques, 19
- Modal constant, 139, 234
- Modal control, 198–201, 202–206, 326–328
- Modal controllability, 330
- Modal control methods, 198
- Modal coordinates, 130, 200, 202, 346
- Modal damping ratio(s), 76
- Modal design criteria, 318–319
- Modal expansion, 176, 296, 304, 322
- Modal frequency, 138, 232–235
- Modal impedance(s), 346
- Modal input coefficients, 347
- Modal matrix, 75, 128, 129, 132, 173, 175
- Modal model
 - truncated, 335
- Modal observed, 173, 174
- Modal parameters, 153, 240
- Modal participation factors, 318, 323
- Modal pole placement control, 202
- Modal testing, 221–245
- Modal time to peak, 319
- Modal truncation, 333–335
- Mode(s)
 - normal, 68, 75, 76, 153, 281
 - rigid body, 102, 130, 266
 - truncated, 334, 335, 345, 351
- Model(s)
 - modal, 50, 241, 335
 - physical, 50, 241
 - reduced-order (ROM)
 - internally balanced, 196
 - response, 138, 241
 - spatial, 241
 - truncated, 345, 351
- Model reduction, 161–164
- Mode shape(s)
 - first, 68
 - sensitivity of, 255
- Mode(s) of vibration
 - natural, 253
- Modulus
 - complex, 324
- Monotonicity principle, 308
- Monotonicity theorem
 - second, 309
- Moore–Penrose inverse, 363
- Motion
 - periodic, 2, 4, 9
 - simple harmonic, 1
- Multiple degree of freedom (MDOF) system, 52, 57, 58, 93, 101, 160
- Multiple-input, multiple-output system (MIMO), 192
- Natural boundary conditions, 270, 335
- Natural coordinates, 130
- Natural frequency(ies)
 - damped, 6, 75, 233
 - sensitivity, 155, 157, 159, 166, 222
 - undamped, 10, 20, 67, 76, 153
- Natural frequency of vibrations, 63
- Natural mode(s) of vibration, 253
- Negative definite matrix, 42, 104, 105, 185
- Negative semidefinite matrix, 42
- Neutral plane, 267
- Nodal displacement vector, 339
- Nodal force vector, 339
- Node(s)
 - connecting, 343
- Nongyroscopic system
 - damped, 43
 - undamped conservative, 158
- Nonhomogeneous response, 132
- Nonhomogeneous system, 123
- Nonlinear equation, 52
- Nonlinear programming, 148
- Nonlinear spring, 27, 28
- Nonmodal distributed control, 328–329
- Nonnegative definite matrix, 42
- Nonsingular matrix, 61, 72, 73, 191, 199
- Nontrivial solution, 59, 251

- Norm
 - controllability, 174, 193
 - of a matrix, 84
- Normal coordinates, 130
- Normalization, 278, 317
- Normalized eigenfunction, 278, 280, 317
- Normalized eigenvector, 62, 70, 130, 157
- Normalized vector, 130
- Normal mode, 68, 75, 76, 281
- Normal mode system, 75, 76, 281
- Norm convergence, 294
- Normed linear space, 293, 294, 295
- Null space, 103–104, 297
- Nyquist frequency, 227
- Nyquist plot, 17, 18, 235

- Objective function, 148, 151
- Observability, 171–176
- Observability grammian, 193
- Observability matrix, 173, 174, 240
- Observation spillover, 201, 352
- Observer
 - Luenberger, 190
 - state, 186, 187, 189
- One-to-one operator, 298
- Open-loop control, 25, 26
- Open-loop estimator, 186
- Open-loop system, 25, 158, 169, 203, 353
- Operator
 - adjoint, 299
 - biharmonic, 267
 - bounded, 298, 299
 - coercive, 306
 - compact, 303–304
 - continuous
 - completely, 303
 - damping, 271
 - equality, 297
 - formally self-adjoint, 300
 - integral, 287, 298, 303
 - inverse, 284, 298
 - Laplace, 264
 - linear functional, 299
 - mass, 271
 - one-to-one, 298
 - positive definite, 302, 315
 - positive semidefinite, 42, 302
 - self-adjoint, 300, 301, 303
 - stiffness, 256, 271, 279
- Optimal control, 179–185
- Optimization, 148–153
- Orthogonality, 71, 253, 293
- Orthogonally similar matrix, 62
- Orthogonal matrix, 70, 76, 89, 130, 181
- Orthogonal vectors, 60, 82, 293
- Orthonormal eigenfunction, 303
- Orthonormal vectors, 61, 67

- Oscillation
 - output feedback, 114
 - output feedback control, 189, 346
 - period of, 14, 19
- Overdamped response, 7
- Overdamped structure, 7, 8, 78, 310, 311
- Overdamped system, 8, 78
- Overshoot, 13, 206, 326

- Parseval's equality, 297
- Participation factors
 - modal, 318
- Particular solution, 9, 131
- Passive control, 25–26, 158, 324–326
- Passive system, 43
- Peak-picking
 - quadrature, 21, 22
- Peak-picking method, 21, 233
- Peak resonance, 11
- Peak time, 13, 319
- Performance index, 179, 180
- Performance robustness, 206
- Period of oscillation, 14, 19
- Periodic motion, 2, 4, 9
- Perturbed matrix, 86
- Pervasively damped system, 107
- Pflüger's rod, 47
- Phase shift, 2, 9, 17, 318
- Physical model, 50, 241
- Piecewise continuous function, 287
- Piezoelectric polymer, 328
- Plant, 16, 26, 35, 169
- Plate vibrations, 264, 270
- Plot
 - Argand plane, 17
 - Bode
 - magnitude, 21
 - phase, 18
 - Nyquist, 17, 18, 235
- Pole(s), 15, 16, 216
- Pole placement, 158
- Position feedback, 49, 208–211
- Positive definite matrix, 65, 89, 107, 112, 113, 193
- Positive definite operator, 303
- Positive semidefinite matrix, 117
- Positive semidefinite operator, 42, 46, 83, 102, 105, 302
- Power spectral density (PSD), 231
- Principle
 - Courant minimax, 307
 - monotonicity, 308, 309
 - superposition, 123
- Principle minor of a matrix, 65, 117
- Proportionally damped system, 107
- PSD, 231
- Pseudoconservative system, 108
- Pseudoinverse, 363
- Pseudosymmetric Matrix, 108
- Pseudosymmetric system, 108

- Quadratic form of a matrix, 42, 46, 104
- Quadrature peak picking, 21, 22
- Q value, 12

- Range, 27, 152, 224, 297
- Range space, 297
- Rank
 - column, 361
 - matrix, 60, 104, 193, 361
 - row, 361
- Ratio
 - damping
 - modal, 76, 139, 153, 166
 - transmissibility, 146, 147
 - Rayleigh damping, 75
 - Rayleigh quotient, 82, 306, 307, 335, 337
- Realization
 - irreducible, 191, 192
 - minimal, 191
 - system, 190
- Reanalysis, 155
- Receptance, 138, 139, 233–234, 235, 241
- Receptance matrix, 138, 140, 241
- Reciprocity, 139
- Redesign, 155–157
- Reduced order model (ROM)
 - internally balanced, 196
- Reduction
 - Guyan, 164, 192
 - model, 161–164
- Relative stability, 160, 161
- Residual, 334
- Residue, 139
- Residue matrix, 139
- Resolvent matrix, 124, 127
- Resonance
 - peak, 11
- Resonance sharpness factor, 12
- Resonance testing, 19
- Response
 - critically damped, 8
 - forced, 8–14, 123–142, 315–331
 - frequency, 16, 17, 21, 138–140
 - impulse, 13, 14
 - nonhomogeneous, 123
 - overdamped, 7
 - speed of, 160
 - steady state, 9, 13, 17, 24
 - total, 133, 150
 - total time, 10, 251
 - transient, 9, 13, 14, 123, 324
 - underdamped, 6
- Response bounds, 136–137
- Response model, 138, 140, 241
- Riccati equation, 181
- Riccati matrix, 181
- Riemann integration, 291
- Riemann–Lebesgue lemma, 296
- Riesz–Fischer theorem, 296
- Riesz representation theorem, 299–300
- Right eigenvector, 71
- Right generalized inverse, 178
- Right inverse, 362
- Right singular vectors, 193
- Rigid body mode, 102
- Rise time, 160
- Ritz–Galerkin approximation, 335–337
- Robustness
 - performance, 206
 - stability, 206
- Robust system, 206
- ROM, 195
- Root mean square value, 229, 230
- Roots
 - characteristic, 57
 - latent, 74
- Row rank, 361

- Sampling theorem, 227
- SDOF, 1, 233
- Second method of Lyapunov, 101, 102
- Second monotonicity theorem, 309
- Self-adjoint operator
 - formally, 300
- Self excited vibrations, 22, 35
- Semidefinite damping, 103–104, 107, 113, 119, 172
- Sensitivity
 - design, 155
 - eigensolution, 155
 - of mode shapes, 155
 - of natural frequency, 155, 157
- Separable Hilbert space, 295
- Separation of variables, 250, 254, 269–270, 271, 276, 278, 280, 282, 284, 291, 320, 336
- Separation theorem
 - Sturmian, 83
- Settling time, 14, 24, 160, 206
- Shaft vibration, 257
- Shannon’s sampling theorem, 227
- Shape
 - mode
 - first, 68
 - sensitivity of, 155, 157
- Shape function, 339, 340, 342
- Shift, 61
- Signal
 - average, 229–230
 - stationary, 229
- Signal conditioner, 224
- Signal mean, 230
- Sign variable matrix, 42
- Similar matrix, 61–62, 64, 72
- Similarity transform, 61, 73
- Similarity transformation matrix, 61, 71, 73, 76, 108, 162
- Simple harmonic motion, 1
- Simple lambda matrix, 74–75, 93, 133
- Single degree of freedom (SDOF), 1

- Single-input, single-output system (SISO), 160, 186, 190, 204, 210
- Singular matrix, 45, 46, 59, 63, 91, 102, 110, 115, 193, 194, 362
- Singular-value decomposition (SVD), 194
- Singular values, 193–195, 197, 208, 215, 240, 362–363
- Singular vectors
 - left, 193
 - right, 193
- SISO system, 204, 210
- Skew-symmetric matrix, 41, 46, 48
- Solution
 - homogeneous, 9, 115, 123, 129, 133, 185
 - nontrivial, 59, 251, 252, 266
 - particular, 9–10, 30, 131, 133, 134
 - trivial, 5, 251, 280
- Space
 - Banach, 294
 - complete, 296
 - Hilbert, 291, 295
 - linear
 - complete, 294
 - normed, 293–294
 - null, 103–104, 107, 109, 297, 298, 303
 - range, 297
 - state, 44, 116, 123, 198, 329
 - vector, 40, 292, 295, 361
- Span, 60
- Spanning set, 295
- Spatial model, 241
- Spectral coefficient, 225, 227, 228
- Speed of response, 160, 326
- Spillover
 - control, 201, 352
 - observation, 201, 352
- Spring
 - linear, 27–28, 262, 292, 293, 294, 297, 361
 - nonlinear, 27–28
- Spring–mass–damper system, 4–5, 8, 9, 28
- Spring–mass system, 1, 81, 146, 244, 321
- Square integrable function, 295
- Square matrix, 40, 41, 58, 61, 72, 108, 109, 343
- Square root of a matrix, 78
- Stability
 - asymptotic, 103–104, 114, 117, 172, 184, 185, 186
 - bounded, 135
 - bounded-input, bounded-output (BIBO), 23, 134–135
 - closed loop, 210
 - conservative system, 101
 - damped system, 22
 - forced response, 23, 134
 - gyroscopic system, 104
 - Lagrange, 24, 135, 138
 - Lyapunov, 24, 99, 100
 - marginal, 22
 - relative, 160, 161
 - state space, 116
- Stability boundary(ies), 118, 119
- Stability margin, 161
- Stability robustness, 206–208
- Stable equilibrium, 99, 103
- Stable system
 - marginally, 22, 120
- State feedback, 26, 44, 175–176, 181, 182, 186, 187, 189–190, 200, 326
- State matrix, 44
- State observer, 186, 187, 189
- State space, 44, 116, 123, 198, 329
- State space stability, 116
- State transition matrix, 127
- State variable feedback, 170, 176, 190, 202, 207
- State vector
 - estimated, 186–187, 189
- Static deflection, 2, 24, 150, 284
- Stationary signal, 229
- Steady state response, 9–10, 13, 14, 16, 17, 24, 26, 127, 137–138, 146, 147, 148, 150, 160, 270, 275
- Step function, 12, 13, 24
- Stiffness
 - dynamic, 209, 235–236, 244, 342, 343, 353
 - Kimball–Lovell complex, 325
- Stiffness influence coefficient, 50
- Stiffness matrix
 - dynamic, 353
 - element, 339
 - global, 342
- Stiffness operator, 256, 271, 336
- Stinger, 223
- Strain gauge, 224–225
- Strong convergence, 294
- Structural control, 1, 169, 208, 345, 353
- Structural modification, 155, 158
- Structure
 - critically damped, 8, 311
 - layered, 268, 325
 - mixed damped, 311, 317
 - overdamped, 8
 - underdamped, 7, 234
- Sturmian separation theorem, 83
- Subspace, 297
- Substructure analysis, 342
- Superposition principle, 123
- SVD, 194
- Symmetric matrix, 42, 64, 67
- Symmetrizable matrix, 112
- Symmetrizable system, 108, 110, 119
- System(s)
 - asymmetric, 109,
 - asymptotically stable, 100–101, 103, 107, 109, 117, 120, 185, 193, 194, 207–208
 - balanced
 - internally, 195
 - circulatory, 43, 107–108
 - closed-loop, 25, 169
 - combined dynamical, 320
 - completely state controllable, 172

- conservative
 - gyroscopic, 43
 - undamped nongyroscopic, 63, 128
- control, 44, 169
- critically damped, 8, 77, 80
- distributed parameter, 249
- eigenvalue, 140, 343, 354
- eigenvector, 74, 139–140, 236, 237
- feedback control, 44
- gyroscopic
 - conservative, 47, 106
 - damped, 45, 106, 119
- hybrid, 320
- internally balanced, 195
- lumped parameter, 39, 123
- modal coordinated, 199, 348
- multiple degree of freedom (MDOF), 39, 52, 54, 57, 58, 79, 80, 93, 101, 138, 153, 160, 233
- multiple-input, multiple-output (MIMO), 169, 192
- nongyroscopic
 - damped, 43, 128, 132
 - undamped
 - conservative, 63
- nonhomogeneous, 123
- normal mode, 75, 76, 281
- open-loop, 25, 115, 158, 169, 203, 353, 354
- overdamped, 7, 8, 78
- passive, 43
- pervasively damped, 107
- proportionally damped, 75, 107
- pseudoconservative, 108
- pseudosymmetric, 108, 109
- robust, 206
- single degree of freedom (SDOF), 1 *passim*
- single-input, single-output (SISO), 160, 186
- spring–mass, 1
- spring–mass–damper, 4
- stable
 - marginally, 22, 120
- symmetrizable, 108, 109
- undamped gyroscopic, 43, 104–105, 107
- underdamped, 7, 12, 13, 14, 19, 30, 32, 78, 91, 136
- System identification theory, 222
- System realization, 190

- Test
 - Hurwitz, 117
- Testing
 - modal, 221
 - resonance, 11, 19
 - vibration, 1, 15, 18, 221
- Theorems
 - enclosure, 308–309
 - expansion, 69, 296
 - Jordan’s, 72
 - KTC, 107, 110
 - Riesz–Fischer, 296
 - Riesz representation, 299, 300
 - second monotonicity, 309
 - separation, 83, 187
 - Shannon’s sampling, 227
 - Sturmian separation, 83
- 3dB down point, 11, 21
- Time
 - modal, 319
 - peak, 13, 24
 - rise, 160
 - settling, 14, 24, 160, 206
- Time constant, 160
- Timoshenko beam equations, 260
- Torsional vibration, 257
- Total response, 123, 133, 160
- Total time response, 10
- Trace of matrix, 73
- Tracking problem, 180
- Transducer, 222
- Transfer function, 14, 191
- Transform
 - Fourier
 - digital, 225, 226, 227, 228, 238
 - fast (FFT), 225, 228
 - Laplace
 - inverse, 26, 124, 125, 127, 191, 283
- Transformation
 - similarity, 61, 71, 73, 76, 108, 194
- Transform methods, 282
- Transient response, 9, 13–14, 133, 160, 324
- Transition matrix
 - state, 127
- Transmissibility, 146
- Transmissibility curves, 146
- Transmissibility ratio, 146
- Transpose
 - conjugate
 - complex, 4, 6, 22, 62, 75, 293, 311
 - of a matrix, 41, 175
 - of a vector, 40, 75
- Transverse vibration, 260, 267, 268, 328
- Trial functions, 335–337
- Triangle inequality, 293, 294
- Trivial solution, 5, 251–252, 280
- Truncated modal model, 335
- Truncated modes, 334, 345
- Tuned absorber, 146, 148

- Unconstrained layer damping, 325
- Undamped gyroscopic system, 43, 104, 105, 107
- Undamped natural frequency, 10, 20, 78, 153
- Undamped nongyroscopic
 - conservative system, 63, 128
- Underdamped response, 6
- Underdamped structure, 12, 241
- Underdamped system, 7, 13, 14, 19, 30, 32, 33, 78, 91
- Undetermined coefficients
 - method of, 9
- Uniformly bounded sequence, 303
- Unit impulse function, 12

376 INDEX

- Units, 357
- Unit vector, 60, 61
- Unperturbed matrix, 86
- Upper triangular matrix, 72, 89

- Variation of parameters, 125, 126, 130
- Vector(s)
 - basis, 60
 - complete set, 66
 - conjugate transpose, 62, 65
 - control, 170
 - coordinates, 128
 - dependent, 60
 - independent, 60, 66, 71
 - latent, 74, 75
 - linearly independent, 60, 62, 64
 - nodal displacement, 339
 - nodal force, 339
 - normalized, 62, 68, 70, 76, 83
 - orthogonal, 60
 - orthonormal, 61, 67, 68
 - singular
 - left, 193
 - right, 193
 - state
 - estimated, 185–190
 - transpose, 40, 75
 - unit, 60–61, 258, 284
- Vector space, 40, 292, 295, 361

- Velocity
 - initial, 3, 6, 13, 41, 98, 129, 283
- Velocity feedback, 44, 49, 326
- Vibration(s)
 - beam
 - layered, 268, 326
 - control, 24, 180, 215, 325, 328, 359
 - design, 66, 145, 148, 180, 272, 331, 357
 - longitudinal, 256, 260, 271, 276, 282
 - membrane, 265, 270
 - modes, 68, 253, 316, 330
 - natural frequencies, 64, 71, 83, 158, 253
 - natural modes, 253
 - plate, 264, 270
 - self-excited, 22, 35
 - shaft, 257
 - string, 249
 - torsional, 257
 - transverse, 260, 267, 268, 328
- Vibration absorber, 24, 145, 146, 147, 148, 158, 209
- Vibration isolation, 145, 146, 147
- Vibration testing, 221
- Viscous damping, 270
- Viscous damping matrix, 41

- Weighting matrices, 180, 182, 183, 214
- Window
 - Hanning, 228, 229
- Window function, 228







